

Series LR digital proportional servo valves

3/3-way directly operated servo valves for the flow (LRWD2), pressure (LRPD2) and position (LRXD2) control



Series LR digital proportional servo valves are direct driven 3/3-way valves with a patented rotating spool system with closed loop control circuit. The electronic board is integrated into the valve's body ready to connect.

Series LR*D2 digital proportional servo valve has been designed to be as compact as possible in order to save space and to be mounted on a DIN-rail.

Thanks to this new digital version, the valve can be configurated through a USB connection according to different requirements.

- » Digital version which is completely configurable through micro USB
- » Rotating spool system with a metal to metal seal
- » High flow rate
- » Electronic control to ensure high precision in the flow control
- » 3-way-function with 4 6 mm nominal diameters
- » Compact version for cabinet mounting on DIN-rail
- » Position control version

GENERAL DATA

 Power supply
 24 V DC +/- 10%, max absorption 1.5 A

 Command signal
 +/- 10 V

 0-10 V
 4-20 mA

Hysteresis1% FS LRWD2 - 0,2% FS LRPD2Linearity1% FS LRWD2 - 0.3% FS LRPD2Switching timesee the following pagesWorking temperaturefrom 0 to 50° C

Working temperature from 0 to 50° C
Relative humidity of air max. 90%
Direction of assembly any

Maximum flow see the diagrams on the following pages

Medium filtered compressed air, unlubricated, according to ISO 8573-1 class 3.4.3, inert gas

Supply pressure -0.9 to 10 bar

Leakage< 1% of maximum flow rate</th>Electrical connectionmale connector M12 8 poles

Hardware configuration port micro USB



CODING EXAMPLE

L I	R W	D	2	-	3	4	-	1	-	Α	-	00
L	SERIES: L = proportion	al servo valves										
R	TECHNOLOGY: R = rotating spool											
W	VERSION: W = flow cont P = pressure co X = position co	ntrol										
D	ELECTRONICS: D = digital											
2	MODEL: 2 = compact D	N-RAIL										
3	FUNCTION: 3 = 3/3-way											
4	NOMINAL DIAMETER: 4 = 4 mm 6 = 6 mm											
1	COMMAND SIG 1 = +/- 10 V 2 = 0 - 10 V 5 = 4 - 20 mA	NAL (Setpoint):										
Α	4 = 0 - 5V (LRP	PD2 and LRXD2 or D2 and LRXD2 onl RPD2 and LRXD2	y)		B = 1 D = 1 E = 2	nternal encod . bar (internal .0 bar (interna 50 mbar (inte 1/-1 bar (inte	sensor - LRPD Il sensor - LRP rnal sensor - I	D2 only) PD2 only) LRPD2 only)				
00	CABLE: 00 = no cable				2R = 5F =	straight cable 90° cable of 2 straight cable	m of 5 m					

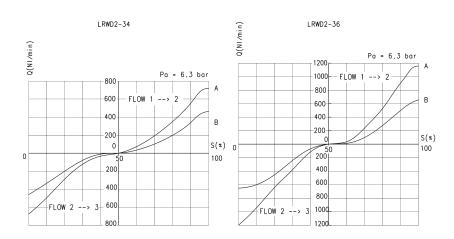
5R = 90° cable of 5 m

FLOW DIAGRAMS FOR VALVES LRWD2-34 AND LRWD2-36

LEGEND:

A = free flow

A = free flow
B = \Delta P1
Q = flow (Nl/min)
S = set point (%)
Pa = inlet pressure (bar)



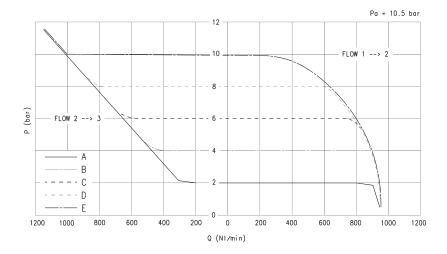
RESPONSE TIMES ACCORDING TO THE COMMAND SIGNAL IN COMPLIANCE WITH THE ISO 10094-2 STANDARD						
COMMAND SIGNAL	-5% ÷ +5%	+5% ÷ -5%	-25% ÷ +25%	+25% ÷ -25%	-90% ÷ +90%	+90% ÷ -90%
Time [ms] LRWD2-34	4	5	6	9	10	10
Time [ms] LRWD2-36	5	5	6	6	10	10

^{*} closed valve with SET POINT = 0 loaded valve with SET POINT = + exhaust valve with SET POINT = -



FLOW DIAGRAMS FOR VALVE LRPD2-34

LEGEND: P = regulated pressure (bar) F = flow (NI/min) Pa = inlet pressure (bar)



RESPONSE TIMES WITH COMMAND SIGNAL BETWEEN 0% AND 100% IN COMPLIANCE WITH ISO 10094-2 STANDARD						
	Without volume	Volume 0,5 l	Volume 2 l			
Filling [ms]	24	313	1841			
Exhaust [ms]	35	663	3640			

valve with SET POINT = 0% and regulated pressure = 0 bar

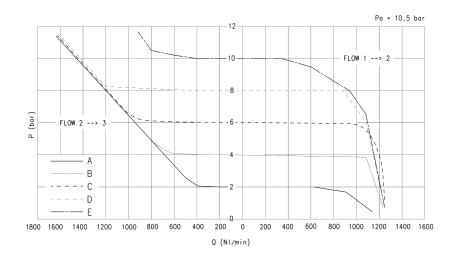
valve with SET POINT = 100% and regulated pressure = maximum pressure

(example: 10 - 1 bar or 250 mbar)

FLOW DIAGRAMS FOR VALVE LRPD2-36

P = regulated pressure (bar) F = flow (Nl/min)

Pa = inlet pressure (bar)



RESPONSE TIMES WITH COMMAND SIGNAL BETWEEN 0% AND 100% IN COMPLIANCE WITH ISO 10094-2 STANDARD					
Without volume Volume 0,5 l Volum					
Filling [ms]	20	263	1560		
Exhaust [ms]	32	357	1905		

valve with SET POINT = 0% and regulated pressure = 0 bar

valve with SET POINT = 100% and regulated pressure = maximum pressure



Series LRXD2 - pneumatic and electrical schemes for the installation

The LRXD2 servo valves are proportional valves with a high-precision integrated control for the positioning of pneumatic cylinders. The valves include a patented 3-way system based on the rotating spool principle with electronic control of the spool position. The servo pneumatic closed loop system allows the control of the position through the feedback of the external positioning sensor or of the Camozzi 6PF cylinder with the integrated linear transducer.

The electronic board which is integrated in the valve body manages speed and acceleration directly.

The Master valve Mod. LRXD2 is equipped with a proper signal to command a LRWD2 valve that will work as a slave-valve.

Configuration for the position control with two valves (Fig. 1)

A = Slave LRWD2-3*-2-A-00 - B = Master LRXD2-3*-*-4-00 - C = 6PF cylinder...

Configuration for the position control with a LRXD2 valve (Fig. 2)

A = Master LRXD2-3*-*-4-00 - B = PR104-... - C = 6PF cylinder...



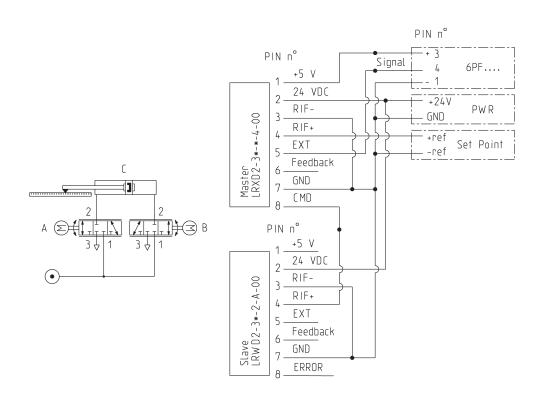
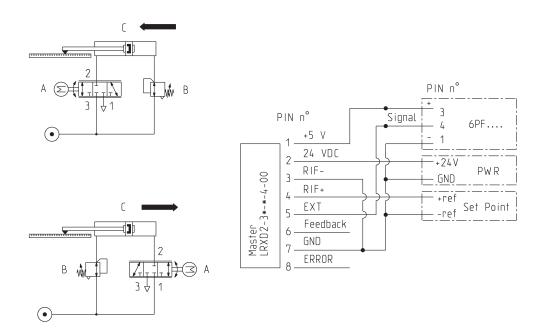


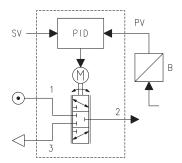
Fig.2

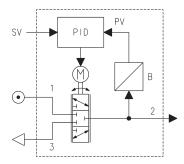




Series LRPD2 - pneumatic scheme for the installation

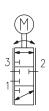
SV = setpoint value PV = process value B = sensor PID = proportional control, integrative, derivative



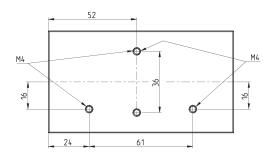


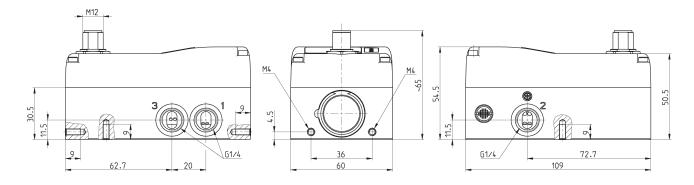
CAMOZZI Automation

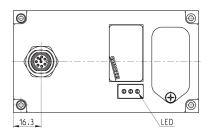
Series LR digital proportional servo valves - dimensions

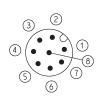


The detailed user and maintenance manual and the Hardware configuration Software of the valve is available online at http://catalogue.camozzi.com.









PIN	SIGNAL		DESCRIPTION
1	+5V		+5V power supply for external potentiometer transducer (ref. GND). If used, it is necessary to connect RIF- with GND.
2	24 V DC		24V DC power supply (logic and motor): connect to the positive pole of the 24V DC power supply (ref. GND)
3	RIF-		GND reference or NEGATIVE pole of the command signal (0-10V / 4-20mA / ±10V)
4	RIF+		POSITIVE reference of the command signal (0-10V / 4-20mA / ±10V)
5	EXT	for LRWD valve:	not used
		for LRXD valve:	feedback signal of the external transducer 0-5V / 0-10V / 4-20mA (ref. RIF-)
		for LRPD valve:	feedback signal of the external transducer 0-5V / 0 -10V / 4 -20mA (ref. RIF-). To be used only with LRPD2 valve versions with external sensor.
6	FBK		feedback signal 0-10V / 4-20mA (ref. GND)
7	GND		common (reference pin 1 and 2): connect to the negative pole of the 24V DC power supply (compulsory)
8	ERR	for LRWD and LRPD valve:	error signal (output) 0-24V (ref. GND)
		for LRXD valve:	command signal 0-10V for slave valve (ref. GND)



Series LR digital proportional servo valves - technical characteristics



* To order the complete code, please replace the asterisk with 4 or 6 according to the desired nominal diameter.

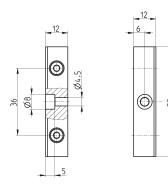
Mod.	Control	Command/Input signal	Sensor/External signal	
LRWD2-3*-1-A-00	flow	+/- 10 V	-	
LRWD2-3*-2-A-00	flow	0-10 V	-	
LRWD2-3*-5-A-00	flow	420 mA	-	
LRPD2-3*-1-2-00	pressure	+/- 10 V	010 V	
LRPD2-3*-2-2-00	pressure	0-10 V	010 V	
LRPD2-3*-5-2-00	pressure	420 mA	010 V	
LRPD2-3*-1-4-00	pressure	+/- 10 V	0 - 5 V	
LRPD2-3*-2-4-00	pressure	0-10 V	0 - 5 V	
LRPD2-3*-5-4-00	pressure	420 mA	0 - 5 V	
LRPD2-3*-1-5-00	pressure	+/- 10 V	420 mA	
LRPD2-3*-2-5-00	pressure	0-10 V	420 mA	
LRPD2-3*-5-5-00	pressure	420 mA	420 mA	
LRPD2-3*-1-B-00	pressure	+/- 10 V	1 bar internal	
LRPD2-3*-2-B-00	pressure	0-10 V	1 bar internal	
LRPD2-3*-5-B-00	pressure	420 mA	1 bar internal	
LRPD2-3*-1-D-00	pressure	+/- 10 V	10 bar internal	
LRPD2-3*-2-D-00	pressure	0-10 V	10 bar internal	
LRPD2-3*-5-D-00	pressure	420 mA	10 bar internal	
LRPD2-3*-1-E-00	pressure	+/- 10 V	250 mbar internal	
LRPD2-3*-2-E-00	pressure	0-10 V	250 mbar internal	
LRPD2-3*-5-E-00	pressure	420 mA	250 mbar internal	
LRPD2-3*-1-F-00	pressure	+/- 10 V	+1/-1 bar internal	
LRPD2-3*-2-F-00	pressure	0-10 V	+1/-1 bar internal	
LRPD2-3*-5-F-00	pressure	420 mA	+1/-1 bar internal	
LRXD2-3*-1-4-00	position	+/- 10 V	0-5 V	suitable to work with the 6PF cylinder (see the PNEUMATIC ACTUATION catalogue)
LRXD2-3*-2-4-00	position	0-10 V	0-5 V	suitable to work with the 6PF cylinder (see the PNEUMATIC ACTUATION catalogue)
LRXD2-3*-5-4-00	position	420 mA	0-5 V	suitable to work with the 6PF cylinder (see the PNEUMATIC ACTUATION catalogue)
LRXD2-3*-1-2-00	position	+/- 10 V	0-10 V	
LRXD2-3*-2-2-00	position	0-10 V	0-10 V	
LRXD2-3*-5-2-00	position	420 mA	0-10 V	
LRXD2-3*-1-5-00	position	+/- 10 V	420mA	
LRXD2-3*-2-5-00	position	0-10 V	420mA	
LRXD2-3*-5-5-00	position	420mA	420mA	

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Fixing foot Mod. LRADB



Supplied with: 2x feet 4x screws



Mod.

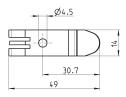
Mounting brackets for DIN-rail Mod. PCF-EN531



DIN EN 50022 (7,5mm x 35mm - width 1)

Supplied with: 2x mounting brackets 2x screws M4x6 UNI 5931 2x nuts





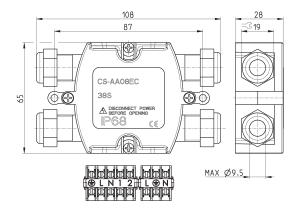
Mod.

PCF-EN531

Electrical tee box Mod. CS-AA08EC



Connection valve-PLC-external transducer



CS-AA08EC

Straight female connector M12 8 poles



For electric supply and commands







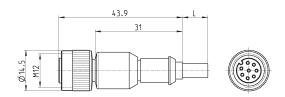
CS-LF08HC

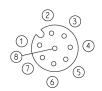
SERIES LR DIGITAL PROPORTIONAL SERVO VALVES

Cable with straight female connector M12 8 poles



For electrical supply and commands



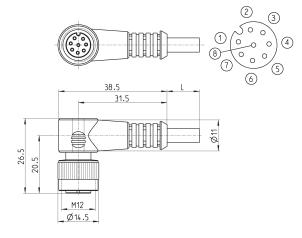


Mod.	Cable length (m)	
CS-LF08HB-C200	2	
CS-1F08HB-C500	5	

Cable with angular (90°) female connector M12 8 poles



For electric supply and commands

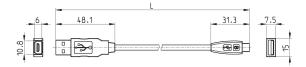


Mod.	Cable length (m)	
CS-LR08HB-C200	2	
CS-LR08HB-C500	5	

USB to Micro USB cable Mod. G11W-G12W-2



For the hardware configuration of the Camozzi products



Mod.	description	connections	material for outer sheath	cable length "L" (m)
G11W-G12W-2	black shielded cable 28 AWG	standard USB to Micro USB	PVC	2